

# Kinetic maximal $L^p$ -regularity

Lukas Niebel, Rico Zacher  
Institute of Applied Analysis, Ulm University

# Kinetic maximal $L^p$ -regularity

# Kinetic maximal $L^p$ -regularity

# Kinetic maximal $L^p$ -regularity

Moving particles

# Kinetic maximal $L^p$ -regularity

Moving particles

Physics/Biology/Economics

# Kinetic maximal $L^p$ -regularity

Moving particles

Physics/Biology/Economics

First order differential operator  $\partial_t + v \cdot \nabla_x$

# Kinetic maximal $L^p$ -regularity

Moving particles

Physics/Biology/Economics

First order differential operator  $\partial_t + v \cdot \nabla_x$

Lebesgue spaces  $L^p$  with  $p \in (1, \infty)$

# Kinetic maximal $L^p$ -regularity

Moving particles

Physics/Biology/Economics

First order differential operator  $\partial_t + v \cdot \nabla_x$

optimal regularity estimates

Lebesgue spaces  $L^p$  with  $p \in (1, \infty)$

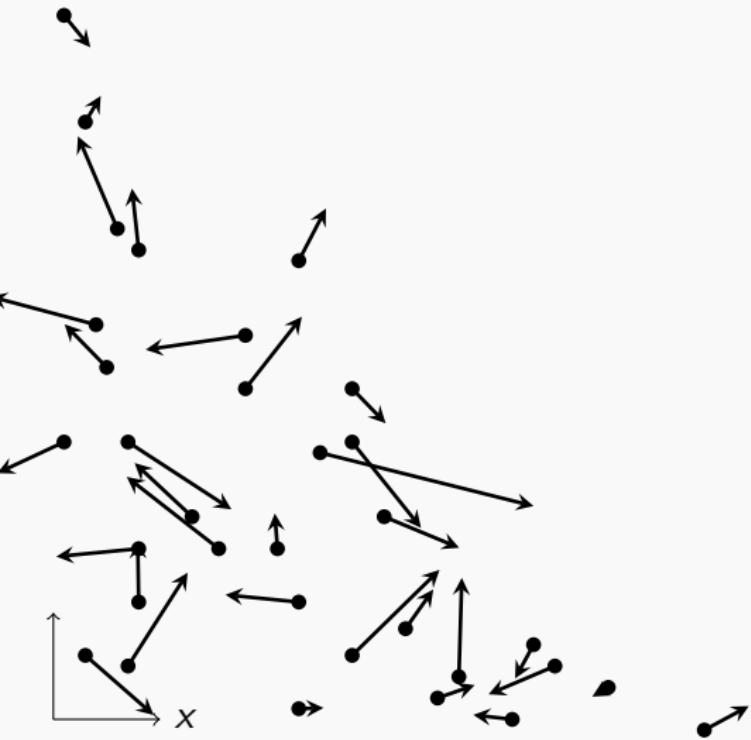
# Kinetic maximal $L^p$ -regularity

Moving particles

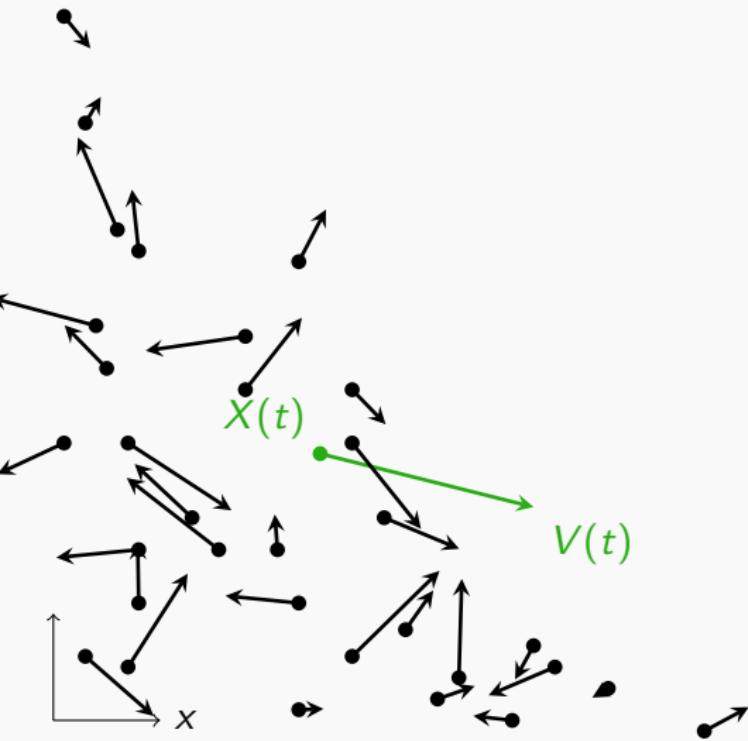
Physics/Biology/Economics

First order differential operator  $\partial_t + v \cdot \nabla_x$

# Particle physics



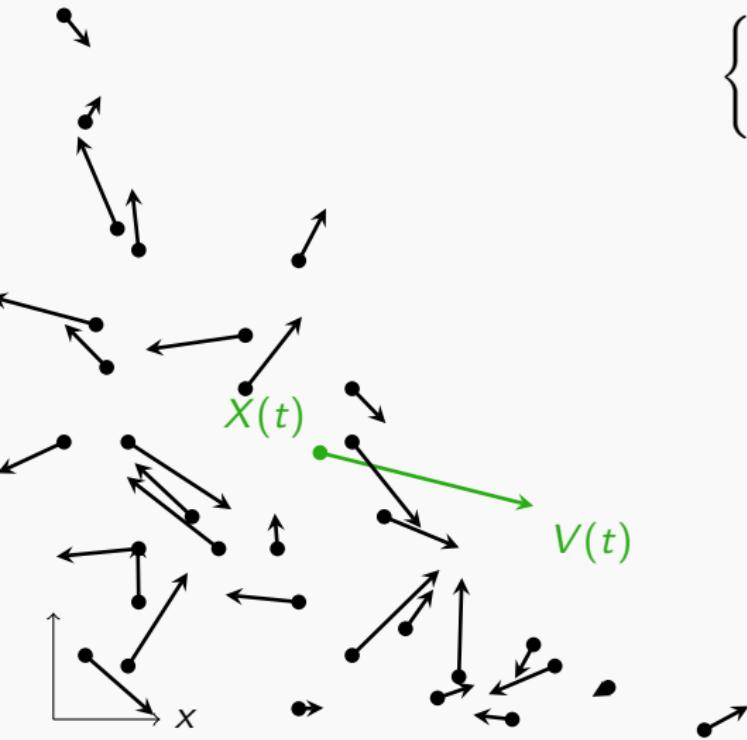
# Particle physics



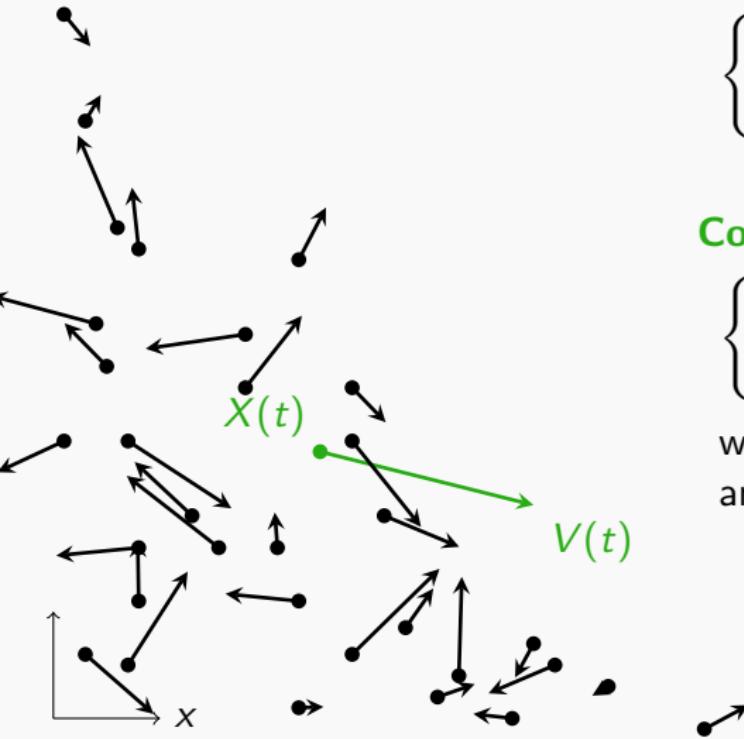
# Particle physics

## Free transport

$$\begin{cases} X(t) = tV_0 + X_0 \\ V(t) = V_0 \end{cases}$$



# Particle physics



## Free transport

$$\begin{cases} X(t) = tV_0 + X_0 \\ V(t) = V_0 \end{cases}$$

## Corresponding PDE

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = 0 \\ u(0) = g \end{cases}$$

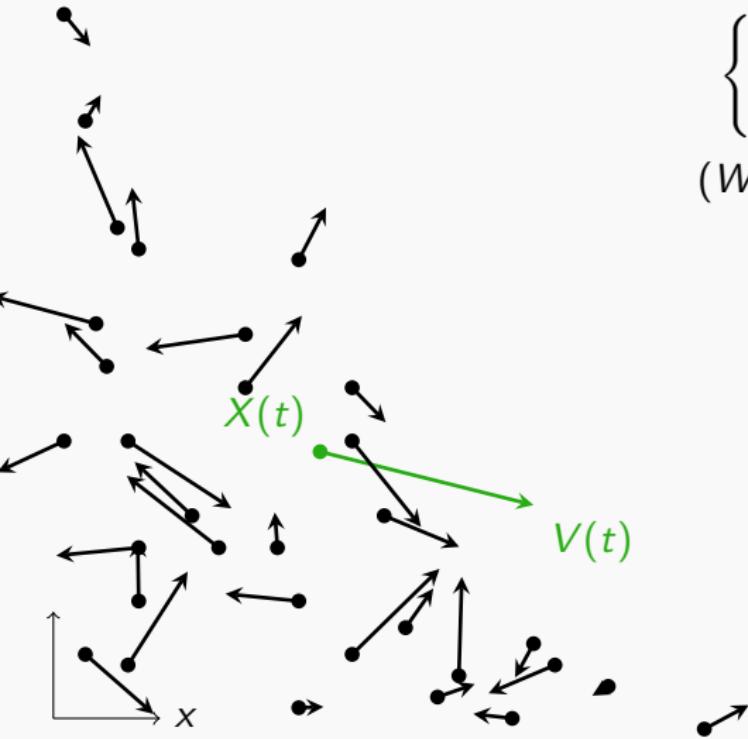
where  $u = u(t, x, v)$  particle density  
and  $g(x, v)$  initial distribution

# Particle physics

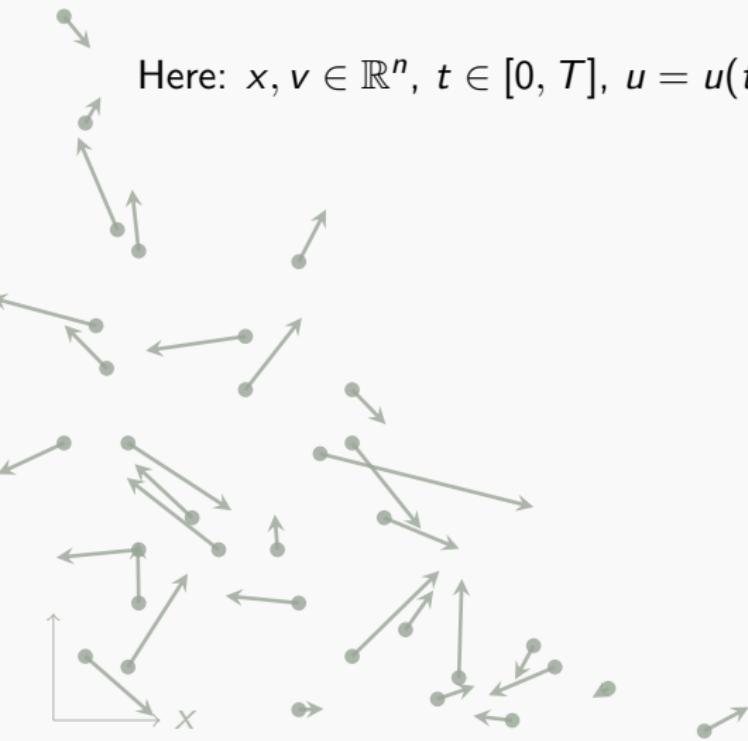
## Simple collision model

$$\begin{cases} X(t) = \int_0^t V(s)ds + X_0 \\ V(t) = W(t) + V_0 \end{cases}$$

$(W(t))_{t \geq 0}$  Wiener process



# Kolmogorov equation



Here:  $x, v \in \mathbb{R}^n$ ,  $t \in [0, T]$ ,  $u = u(t, x, v)$  particle density

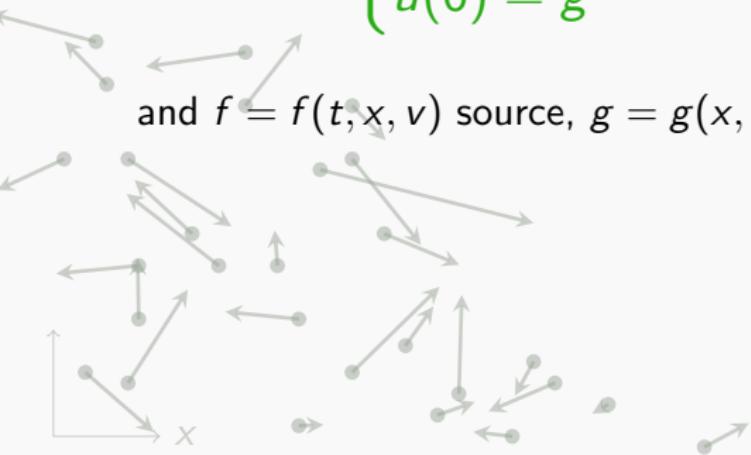
# Kolmogorov equation



Here:  $x, v \in \mathbb{R}^n$ ,  $t \in [0, T]$ ,  $u = u(t, x, v)$  particle density

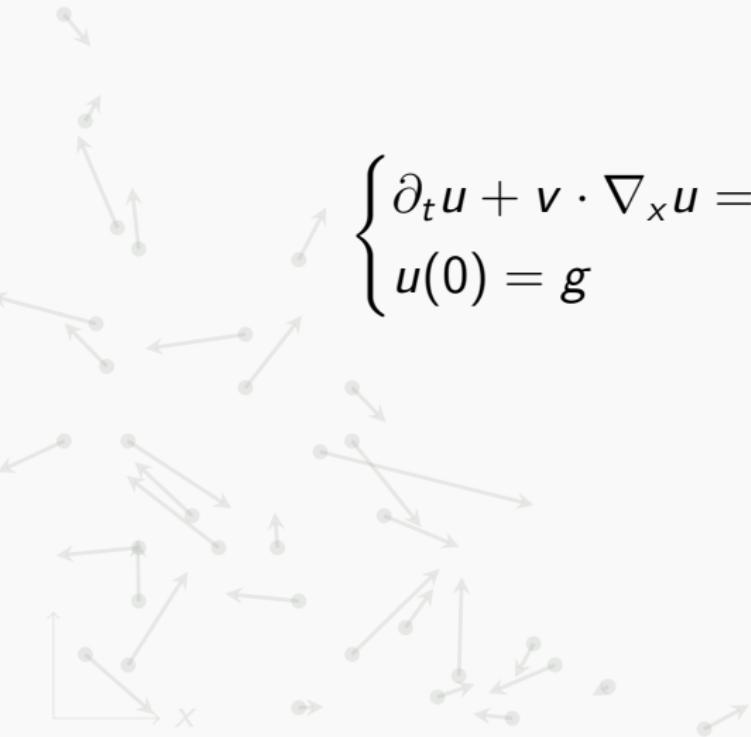
$$\begin{cases} \partial_t u + v \cdot \nabla_x u = \Delta_v u + f \\ u(0) = g \end{cases}$$

and  $f = f(t, x, v)$  source,  $g = g(x, v)$  initial datum.



# Kolmogorov equation

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = \Delta_v u + f \\ u(0) = g \end{cases}$$



## Kolmogorov equation

2nd order PDE, degenerate, unbounded lower order term  
reminds of Ornstein-Uhlenbeck equation  
hypoelliptic, Hörmander operator

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = \Delta_v u + f \\ u(0) = g \end{cases}$$

# Kolmogorov equation

2nd order PDE, degenerate, unbounded lower order term  
reminds of Ornstein-Uhlenbeck equation  
Hörmander operator - hypoelliptic

$$\begin{cases} X_0 u = \sum_{i=1}^n X_i^2 u + f \\ u(0) = g \end{cases}$$

where  $X_0 = \partial_t + v \cdot \nabla_x$  and  $X_i = \partial_{v_i}$

$$[\partial_{v_i}, \partial_t + v \cdot \nabla_x] u = \partial_{v_i}(\partial_t + v \cdot \nabla_x) u - (\partial_t + v \cdot \nabla_x) \partial_{v_i} u = \partial_{x_i} u$$

# Kolmogorov equation

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = \Delta_v u + f \\ u(0) = g \end{cases}$$

Scaling:  $\lambda \mapsto (\lambda^2 t, \lambda^3 x, \lambda v)$

Translation:  $(t_0, x_0, v_0) \mapsto (t - t_0, x - x_0 - (t - t_0)v, v - v_0)$

## Kolmogorov equation

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = \Delta_v u + f \\ u(0) = g \end{cases}$$

## Kolmogorov equation

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = \Delta_v u + f \\ u(0) = g \end{cases}$$

**Goal:** Determine function spaces  $X$  for  $f$ ,  $X_\gamma$  for  $g$  and  $Z$  for  $u$  such that there exists a unique solution  $u \in Z$  of the Kolmogorov equation if and only if  $f \in X$  and  $g \in X_\gamma$ .

# Kolmogorov equation

## Kinetic maximal regularity

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = \Delta_v u + f \\ u(0) = g \end{cases}$$

Goal: Determine function spaces  $X$  for  $f$ ,  $X_\gamma$  for  $g$  and  $Z$  for  $u$  such that there exists a unique solution  $u \in Z$  of the Kolmogorov equation if and only if  $f \in X$  and  $g \in X_\gamma$ .

# Kolmogorov equation

Kinetic maximal  $L^p$ -regularity

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = \Delta_v u + f \\ u(0) = g \end{cases}$$

Ansatz:

# Kolmogorov equation

Kinetic maximal  $L^p$ -regularity

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = \Delta_v u + f \\ u(0) = g \end{cases}$$

Ansatz:  $f \in X = L^p((0, T); L^p(\mathbb{R}^{2n}))$  with  $p \in (1, \infty)$ .

# Kolmogorov equation

Kinetic maximal  $L^p$ -regularity

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = \Delta_v u + f \\ u(0) = g \end{cases}$$

Ansatz:  $f \in X = L^p((0, T); L^p(\mathbb{R}^{2n}))$  with  $p \in (1, \infty)$ .

What is the solution space  $Z$ ?

What is the trace space  $X_\gamma$ ?

# Kolmogorov equation

Kinetic maximal  $L^p$ -regularity

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = \Delta_v u + f \\ u(0) = g \end{cases}$$

Ansatz:  $f \in X = L^p((0, T); L^p(\mathbb{R}^{2n}))$  with  $p \in (1, \infty)$ .

What is the solution space  $Z$ ?

What is the trace space  $X_\gamma$ ?

Divide and conquer

## Kolmogorov equation

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = \Delta_v u + f \\ u(0) = 0 \end{cases}$$

Parabolic ansatz - maximal  $L^p$ -regularity

$$Z = \{u : u, \partial_t u, \Delta_v u - v \cdot \nabla_x u \in L^p((0, T); L^p(\mathbb{R}^{2n}))\}$$

# Kolmogorov equation

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = \Delta_v u + f \\ u(0) = 0 \end{cases}$$

Parabolic ansatz

$$Z = \{u : u, \partial_t u, \Delta_v u - v \cdot \nabla_x u \in L^p((0, T); L^p(\mathbb{R}^{2n}))\}$$

The desired characterisation fails.

# Kolmogorov equation

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = \Delta_v u + f \\ u(0) = 0 \end{cases}$$

Parabolic ansatz

$$Z = \{u : u, \partial_t u, \Delta_v u - v \cdot \nabla_x u \in L^p((0, T); L^p(\mathbb{R}^{2n}))\}$$

The desired characterisation fails.

$$\text{Indeed: } \sigma(\Delta_v - v \cdot \nabla_x) = \{\lambda \in \mathbb{C} : \operatorname{Re}\lambda \leq 0\}$$

# Kolmogorov equation

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = \Delta_v u + f \\ u(0) = 0 \end{cases}$$

Solution space

$$Z = \{u : u, \partial_t u + v \cdot \nabla_x u, \Delta_v u \in L^p((0, T); L^p(\mathbb{R}^{2n}))\}.$$

# Kolmogorov equation

Fundamental solution (Kolmogorov 1934):

$$\Gamma(t, x, v) = \frac{c_n}{t^{2n}} \exp\left(-\frac{1}{t} |v|^2 + \frac{3}{t^2} \langle v, x \rangle - \frac{3}{t^3} |x|^2\right).$$

# Kolmogorov equation

Fundamental solution (Kolmogorov 1934):

$$\Gamma(t, x, v) = \frac{c_n}{t^{2n}} \exp\left(-\frac{1}{t} |v|^2 + \frac{3}{t^2} \langle v, x \rangle - \frac{3}{t^3} |x|^2\right).$$

Solution of Kolmogorov equation with  $g = 0$  is given by

$$u(t, x, v) = \int_0^t \int_{\mathbb{R}^{2n}} \Gamma(t-s, x-y-(t-s)w, v-w) f(s, y, w) d(y, w) ds$$

# Kolmogorov equation

Fundamental solution (Kolmogorov 1934):

$$\Gamma(t, x, v) = \frac{c_n}{t^{2n}} \exp\left(-\frac{1}{t} |v|^2 + \frac{3}{t^2} \langle v, x \rangle - \frac{3}{t^3} |x|^2\right).$$

Solution of Kolmogorov equation with  $g = 0$  is given by

$$u(t, x, v) = \int_0^t \int_{\mathbb{R}^{2n}} \Gamma(t-s, x-y-(t-s)w, v-w) f(s, y, w) d(y, w) ds$$

Singular integral on homogeneous group (Folland-Stein 1974):

$$\|\partial_t u + v \cdot \nabla_x u\|_p + \|\Delta_v u\|_p \leq C \|f\|_p.$$

For every  $f \in L^p((0, T); L^p(\mathbb{R}^{2n}))$  there exists a unique solution  $u \in Z$  of the Kolmogorov equation.

## Kinetic trace

Temporal trace  $u(t)$  is well-defined. In particular

$$\{u: u, \partial_t u + v \cdot \nabla_x u \in L^p((0, T); L^p(\mathbb{R}^{2n}))\} \hookrightarrow C([0, T]; L^p(\mathbb{R}^{2n}))$$

## Kinetic trace

Temporal trace  $u(t)$  is well-defined as

$$\{u: u, \partial_t u + v \cdot \nabla_x u \in L^p((0, T); L^p(\mathbb{R}^{2n}))\} \hookrightarrow C([0, T]; L^p(\mathbb{R}^{2n}))$$

The trace space of  $Z$  is defined as

$$X_\gamma = \{g: \exists u \in Z \text{ with } u(0) = g\}$$

$$\|g\|_{X_\gamma} = \inf_{\substack{u \in Z \\ u(0)=g}} \|u\|_Z.$$

Moreover

$$Z \hookrightarrow C([0, T]; X_\gamma).$$

# Kinetic maximal $L^p$ -regularity

## Definition

We say that  $A: D(A) \subset L^p(\mathbb{R}^{2n}) \rightarrow L^p(\mathbb{R}^{2n})$  admits kinetic maximal  $L^p$ -regularity if for all  $f \in X = L^p((0, T); L^p(\mathbb{R}^{2n}))$  there exists a unique distributional solution

$$u \in Z = \{w : w, \partial_t w + v \cdot \nabla_x w, Aw \in L^p((0, T); L^p(\mathbb{R}^{2n}))\}$$

of the Cauchy problem

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = Au + f \\ u(0) = 0 \end{cases}$$

In particular  $u \in C([0, T]; X_\gamma)$ .

## Kolmogorov equation

Theorem (Folland & Stein 74, Bramanti et al. 10, N. & Zacher 22)

---

The operator  $\Delta_v: H_v^{2,p}(\mathbb{R}^{2n}) \rightarrow L^p(\mathbb{R}^{2n})$ /the Kolmogorov equation admits kinetic maximal  $L^p(L^p)$ -regularity for all  $p \in (1, \infty)$ .

# Kolmogorov equation

## Theorem

For the Kolmogorov equation

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = \Delta_v u + f \\ u(0) = g \end{cases}$$

there exists a unique solution

$$u \in Z = \{w : w, \partial_t w + v \cdot \nabla_x w, \Delta_v w \in L^p((0, T); L^p(\mathbb{R}^{2n}))\}$$

if and only if

(i)  $f \in X = L^p((0, T); L^p(\mathbb{R}^{2n}))$

(ii)  $g \in X_\gamma$ .

Moreover,  $u \in C([0, T]; X_\gamma)$ .

# Kolmogorov equation

## Theorem

For the Kolmogorov equation

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = \Delta_v u + f \\ u(0) = g \end{cases}$$

there exists a unique solution

$$u \in Z = \{w : w, \partial_t w + v \cdot \nabla_x w, \Delta_v w \in L^p((0, T); L^p(\mathbb{R}^{2n}))\}$$

if and only if

(i)  $f \in X = L^p((0, T); L^p(\mathbb{R}^{2n}))$

(ii)  $g \in X_\gamma$ .

Moreover,  $u \in C([0, T]; X_\gamma)$ .

# Kinetic trace

## Kinetic Regularisation (Bouchut 02)

Let  $u \in L^p(\mathbb{R}^{1+2n})$  with  $\partial_t u + v \cdot \nabla_x u \in L^p(\mathbb{R}^{1+2n})$  and  $\Delta_v u \in L^p(\mathbb{R}^{1+2n})$ . Then

$$D_x^{\frac{2}{3}} u \in L^p(\mathbb{R}^{1+2n}).$$

Here:  $D_x^s = (-\Delta_x)^{s/2}$

# Kinetic trace

## Kinetic Regularisation (Bouchut 02)

Let  $u \in L^p(\mathbb{R}^{1+2n})$  with  $\partial_t u + v \cdot \nabla_x u \in L^p(\mathbb{R}^{1+2n})$  and  $\Delta_v u \in L^p(\mathbb{R}^{1+2n})$ . Then

$$D_x^{\frac{2}{3}} u \in L^p(\mathbb{R}^{1+2n}).$$

Recall the scaling:  $\lambda \mapsto (\lambda^2 t, \lambda^3 x, \lambda v)$ .

Here:  $D_x^s = (-\Delta_x)^{s/2}$

# Kinetic trace

Theorem (N. & Zacher 22)

Let  $p \in (1, \infty)$  and  $X_\gamma$  the trace space to

$$Z = \{u : u, \partial_t u + v \cdot \nabla_x u, \Delta_v u \in L^p((0, T); L^p(\mathbb{R}^{2n}))\}.$$

Then

$$X_\gamma \cong B_{pp,x}^{\frac{2}{3}(1-\frac{1}{p})}(\mathbb{R}^{2n}) \cap B_{pp,v}^{2(1-\frac{1}{p})}(\mathbb{R}^{2n}).$$

# Kinetic trace

Theorem (N. & Zacher 22)

Let  $p \in (1, \infty)$  and  $X_\gamma$  the trace space to

$$Z = \{u : u, \partial_t u + v \cdot \nabla_x u, \Delta_v u \in L^p((0, T); L^p(\mathbb{R}^{2n}))\}.$$

Then

$$X_\gamma \cong B_{pp,x}^{\frac{2}{3}(1-\frac{1}{p})}(\mathbb{R}^{2n}) \cap B_{pp,v}^{2(1-\frac{1}{p})}(\mathbb{R}^{2n}).$$

# Kolmogorov equation

Theorem (N. & Zacher 22)

For the Kolmogorov equation

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = \Delta_v u + f \\ u(0) = g \end{cases}$$

there exists a unique solution

$$u \in Z = \{w : w, \partial_t w + v \cdot \nabla_x w, \Delta_v w \in L^p((0, T); L^p(\mathbb{R}^{2n}))\}$$

if and only if

# Kolmogorov equation

Theorem (N. & Zacher 22)

For the Kolmogorov equation

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = \Delta_v u + f \\ u(0) = g \end{cases}$$

there exists a unique solution

$$u \in Z = \{w : w, \partial_t w + v \cdot \nabla_x w, \Delta_v w \in L^p((0, T); L^p(\mathbb{R}^{2n}))\}$$

if and only if

(i)  $f \in X = L^p((0, T); L^p(\mathbb{R}^{2n}))$

(ii)  $g \in X_\gamma = B_{pp,x}^{\frac{2}{3}(1-\frac{1}{p})}(\mathbb{R}^{2n}) \cap B_{pp,v}^{2(1-\frac{1}{p})}(\mathbb{R}^{2n}).$

Moreover,  $u \in C([0, T]; X_\gamma).$

# Extensions

- fractional Kolmogorov equation
- temporal weights
- different base spaces
- variable coefficients

# Fractional Kolmogorov equation

with  $\beta \in (0, 2)$ :

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = -(-\Delta_v)^{\beta/2} u + f \\ u(0) = g. \end{cases}$$

# Fractional Kolmogorov equation

with  $\beta \in (0, 2)$ :

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = -(-\Delta_v)^{\beta/2} u + f \\ u(0) = g. \end{cases}$$

Theorem (Chen & Zhang 18; Huang, Menozzi & Priola 19)

For  $\beta \in (0, 2)$  the operator  $-(-\Delta_v)^{\beta/2}: H_v^{\beta, p}(\mathbb{R}^{2n}) \rightarrow L^p(\mathbb{R}^{2n})$  admits kinetic maximal  $L^p(L^p)$ -regularity for all  $p \in (1, \infty)$ .

# Fractional Kolmogorov equation

with  $\beta \in (0, 2)$ :

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = -(-\Delta_v)^{\beta/2} u + f \\ u(0) = g. \end{cases}$$

Theorem (Chen & Zhang 18; Huang, Menozzi & Priola 19)

For  $\beta \in (0, 2)$  the operator  $-(-\Delta_v)^{\beta/2}: H_v^{\beta, p}(\mathbb{R}^{2n}) \rightarrow L^p(\mathbb{R}^{2n})$  admits kinetic maximal  $L^p(L^p)$ -regularity for all  $p \in (1, \infty)$ .

Theorem (N. & Zacher 22)

$$X_\gamma \cong B_{pp,x}^{\frac{\beta}{\beta+1}(1-\frac{1}{p})}(\mathbb{R}^{2n}) \cap B_{pp,v}^{\beta(1-\frac{1}{p})}(\mathbb{R}^{2n})$$

## Temporal weights

Replace  $L^p((0, T); X)$  with

$$L_\mu^p((0, T); X) = \{u: t^{1-\mu}u \in L^p((0, T); X)\}$$

with  $\mu \in (1/p, 1]$  (Muckenhoupt weight, Prüss & Simonett 04).

# Temporal weights

Replace  $L^p((0, T); X)$  with

$$L_\mu^p((0, T); X) = \{u: t^{1-\mu} u \in L^p((0, T); X)\}$$

with  $\mu \in (1/p, 1]$ . (Muckenhoupt weight, Prüss & Simonett 04)

Advantages:

- Theorem (N. & Zacher 22):

Kinetic maximal  $L_\mu^p$ -regularity is independent of  $\mu \in (1/p, 1]$ .

- for (fractional) Kolmogorov equation:

$$X_{\gamma, \mu} \cong B_{pp,x}^{\frac{\beta}{\beta+1}(\mu - \frac{1}{p})}(\mathbb{R}^{2n}) \cap B_{pp,v}^{\beta(\mu - \frac{1}{p})}(\mathbb{R}^{2n})$$

- treat lower initial value regularity
- allows to observe instantaneous regularisation

## Different base spaces

- Kinetic maximal  $L^p(L^q)$ -regularity for  $-(-\Delta_v)^{\beta/2}$  (& variants)  
with  $p, q \in (1, \infty)$

## Different base spaces

- Kinetic maximal  $L^p(L^q)$ -regularity for  $-(-\Delta_v)^{\beta/2}$  (& variants) with  $p, q \in (1, \infty)$
- Kinetic maximal  $L^p(L_{j,k}^q)$ -regularity for  $-(-\Delta_v)^{\beta/2}$  (& variants) with  $p, q \in (1, \infty)$  and  $j, k \in \mathbb{R}$  where  $L_{j,k}^q$  is weighted with  $(1 + |v|)^j$  and  $(1 + |x| + |v|)^k$

## Different base spaces

- Kinetic maximal  $L^p(L^q)$ -regularity for  $-(-\Delta_v)^{\beta/2}$  (& variants) with  $p, q \in (1, \infty)$
- Kinetic maximal  $L^p(L_{j,k}^q)$ -regularity for  $-(-\Delta_v)^{\beta/2}$  (& variants) with  $p, q \in (1, \infty)$  and  $j, k \in \mathbb{R}$  where  $L_{j,k}^q$  is weighted with  $(1 + |v|)^j$  and  $(1 + |x| + |v|)^k$
- Kinetic maximal  $L^p(X_\beta^s)$ -regularity for  $-(-\Delta_v)^{\beta/2}$  with  $p \in (1, \infty)$  and  $s \geq -1/2$

$$X_\beta^s = \left\{ f \in \mathcal{S}' : \left(1 + |\xi|^\beta + |k|^{\frac{\beta}{\beta+1}}\right)^s \mathcal{F}(f) \in L^2 \right\}$$

## Different base spaces

- Kinetic maximal  $L^p(L^q)$ -regularity for  $-(-\Delta_v)^{\beta/2}$  (& variants) with  $p, q \in (1, \infty)$
- Kinetic maximal  $L^p(L_{j,k}^q)$ -regularity for  $-(-\Delta_v)^{\beta/2}$  (& variants) with  $p, q \in (1, \infty)$  and  $j, k \in \mathbb{R}$  where  $L_{j,k}^q$  is weighted with  $(1 + |v|)^j$  and  $(1 + |x| + |v|)^k$
- Kinetic maximal  $L^p(X_\beta^s)$ -regularity for  $-(-\Delta_v)^{\beta/2}$  with  $p \in (1, \infty)$  and  $s \geq -1/2$ 
$$X_\beta^s = \left\{ f \in \mathcal{S}' : \left(1 + |\xi|^\beta + |k|^{\frac{\beta}{\beta+1}}\right)^s \mathcal{F}(f) \in L^2 \right\}$$

Including a characterisation of the trace space.

## Kolmogorov equation with variable coefficients

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = a(t, x, v) : \nabla_v^2 u + f \\ u(0) = g \end{cases}$$

Under which assumptions on the coefficient  $a(t, x, v)$   
do we obtain kinetic maximal  $L^p$ -regularity?

# Kolmogorov equation with variable coefficients

Theorem (Bramanti et al. 13, N. & Zacher 22)

Let  $a = a(t, x, v) \in L^\infty([0, T] \times \mathbb{R}^{2n}; \text{Sym}(n))$  with  
 $\lambda |\xi|^2 \leq \langle a(t, x, v)\xi, \xi \rangle$  for all  $(t, x, v)$  and  $\xi \in \mathbb{R}^n$ .

# Kolmogorov equation with variable coefficients

Theorem (Bramanti et al. 13, N. & Zacher 22)

Let  $a = a(t, x, v) \in L^\infty([0, T] \times \mathbb{R}^{2n}; \text{Sym}(n))$  with

$\lambda |\xi|^2 \leq \langle a(t, x, v)\xi, \xi \rangle$  for all  $(t, x, v)$  and  $\xi \in \mathbb{R}^n$ . Suppose

$\forall \varepsilon > 0: \exists \delta > 0$  such that  $|t - s| + |x - y - (t - s)v| + |v - w| < \delta$   
implies  $|a(t, x, v) - a(s, y, w)| < \varepsilon$

OR

$\forall \varepsilon > 0: \exists \delta > 0$  such that  $|t - s| + |x - y| + |v - w| < \delta$   
implies  $|a(t, x, v) - a(s, y, w)| < \varepsilon$ .

# Kolmogorov equation with variable coefficients

Theorem (Bramanti et al. 13, N. & Zacher 22)

Let  $a = a(t, x, v) \in L^\infty([0, T] \times \mathbb{R}^{2n}; \text{Sym}(n))$  with

$\lambda |\xi|^2 \leq \langle a(t, x, v)\xi, \xi \rangle$  for all  $(t, x, v)$  and  $\xi \in \mathbb{R}^n$ . Suppose

$\forall \varepsilon > 0: \exists \delta > 0$  such that  $|t - s| + |\textcolor{red}{x} - y - (t - s)v| + |v - w| < \delta$   
implies  $|a(t, x, v) - a(s, y, w)| < \varepsilon$

OR

$\forall \varepsilon > 0: \exists \delta > 0$  such that  $|t - s| + |\textcolor{red}{x} - y| + |v - w| < \delta$   
implies  $|a(t, x, v) - a(s, y, w)| < \varepsilon$ .

# Kolmogorov equation with variable coefficients

Theorem (Bramanti et al. 13, N. & Zacher 22)

Let  $a = a(t, x, v) \in L^\infty([0, T] \times \mathbb{R}^{2n}; \text{Sym}(n))$  with

$\lambda |\xi|^2 \leq \langle a(t, x, v)\xi, \xi \rangle$  for all  $(t, x, v)$  and  $\xi \in \mathbb{R}^n$ . Suppose

$\forall \varepsilon > 0: \exists \delta > 0$  such that  $|t - s| + |x - y - (t - s)v| + |v - w| < \delta$   
implies  $|a(t, x, v) - a(s, y, w)| < \varepsilon$

OR

$\forall \varepsilon > 0: \exists \delta > 0$  such that  $|t - s| + |x - y| + |v - w| < \delta$   
implies  $|a(t, x, v) - a(s, y, w)| < \varepsilon$ .

Then the family of operators  $A(t) = a(t, x, v): \nabla_v^2: H_v^{2,p} \rightarrow L^p$   
admits kinetic maximal  $L_\mu^p(L_{j,k}^q)$ -regularity.

# Fractional Kolmogorov equation with variable density

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = -(-\Delta_v)^{\beta/2} u + f \\ u(0) = g \end{cases}$$

Recall

$$-(-\Delta_v)^{\beta/2} u = c_{n,\beta} \text{ p.v. } \int_{\mathbb{R}^n} \frac{u(t, x, v+h) - u(t, x, v)}{|h|^{n+\beta}} dh$$

# Fractional Kolmogorov equation with variable density

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = -(-\Delta_v)^{\beta/2} u + f \\ u(0) = g \end{cases}$$

Recall

$$-(-\Delta_v)^{\beta/2} u = c_{n,\beta} \text{ p.v. } \int_{\mathbb{R}^n} \frac{u(t, x, v+h) - u(t, x, v)}{|h|^{n+\beta}} a(t, x, v, h) dh$$

# Fractional Kolmogorov equation with variable density

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = A(t)u + f \\ u(0) = g \end{cases}$$

Recall

$$A(t)u = \text{p.v.} \int_{\mathbb{R}^n} \frac{u(t, x, v+h) - u(t, x, v)}{|h|^{n+\beta}} a(t, x, v, h) dh$$

# Fractional Kolmogorov equation with variable density

Theorem (N. 22):

Let  $a = a(t, x, v, h) \in L^\infty([0, T] \times \mathbb{R}^{3n})$  symmetric in  $h$   
with  $0 < \lambda \leq a \leq \Lambda$ ,  $\alpha \in (0, 1)$ ,  $\alpha < \alpha_0 < 1$

$$\sup \frac{|a(t, x, v, h) - a(s, y, w, h)|}{|t-s|^{\alpha_0} + |x-y-(t-s)v|^{\alpha_0} + |v-w|^{\alpha_0}} < \infty.$$

# Fractional Kolmogorov equation with variable density

Theorem (N. 22):

Let  $a = a(t, x, v, h) \in L^\infty([0, T] \times \mathbb{R}^{3n})$  symmetric in  $h$   
with  $0 < \lambda \leq a \leq \Lambda$ ,  $\alpha \in (0, 1)$ ,  $\alpha < \alpha_0 < 1$

$$\sup \frac{|a(t, x, v, h) - a(s, y, w, h)|}{|t-s|^{\alpha_0} + |x-y-(t-s)v|^{\alpha_0} + |v-w|^{\alpha_0}} < \infty.$$

Then, the family of operators

$$A(t)u = \text{p.v.} \int_{\mathbb{R}^n} \frac{u(t, x, v+h) - u(t, x, v)}{|h|^{n+\beta}} a(t, x, v, h) dh$$

admits kinetic maximal  $L_\mu^p(L^p)$ -regularity for all  $p > \frac{n}{\alpha}$ ,  $\mu \in (1/p, 1]$ .

Same trace space as for  $-(-\Delta_v)^{\beta/2}$ .

## Application to quasilinear equations

## Application to quasilinear equations

Think of  $X$  as  $L_{j,k}^q(\mathbb{R}^n)$  and let  $D \subset X$ . Seek solutions in

$$Z(0, T) = \{u: u, \partial_t u + v \cdot \nabla_x u \in L_\mu^p((0, T); X)\} \cap L_\mu^p((0, T); D)$$

of

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = A(u)u + F(u) \\ u(0) = g \end{cases}$$

where

- $g \in X_{\gamma,\mu}$
- $A: X_{\gamma,\mu} \rightarrow \mathcal{B}(D, X)$
- $F: X_{\gamma,\mu} \rightarrow X$

# Application to quasilinear equations

Theorem (N. & Zacher 22):

Assume that

$$-(A, F) \in C_{\text{loc}}^{1-}(X_{\gamma, \mu}; \mathcal{B}(D, X) \times X)$$

-  $A(g)$  admits kinetic maximal  $L_\mu^p(X)$ -regularity.

Then, there exists  $T = T(g)$  and  $\varepsilon = \varepsilon(g) > 0$  such that

$$\begin{cases} \partial_t u + v \cdot \nabla_x u = A(u)u + F(u) \\ u(0) = h \end{cases}$$

admits a unique solution in  $Z(0, T)$  for all  $h \in \overline{B_\varepsilon(g)}^{X_{\gamma, \mu}}$ .  
Moreover, solutions depend continuously on the initial datum.

# Boltzmann equation

$$\partial_t u + v \cdot \nabla_x u = Q(u, u) + \text{l.o.t.},$$

# Boltzmann equation

In Carleman coordinates

$$\partial_t u + v \cdot \nabla_x u = Q(u, u) + \text{l.o.t.},$$

where

$$Q(u, u) = \text{p.v.} \int_{\mathbb{R}^n} \frac{u(t, x, v + h) - u(t, x, v)}{|h|^{n+2s}} m(u)(t, x, v, h) dh$$

# Boltzmann equation

In Carleman coordinates

$$\partial_t u + v \cdot \nabla_x u = Q(u, u) + \text{l.o.t.},$$

where

$$Q(u, u) = \text{p.v.} \int_{\mathbb{R}^n} \frac{u(t, x, v + h) - u(t, x, v)}{|h|^{n+2s}} m(u)(t, x, v, h) dh$$

with

$$m(u)(t, x, v, h) = \int_{w \perp h} u(t, x, v + w) |w|^{\gamma+2s+1} dw$$

and  $s \in (0, 1)$ ,  $\gamma > -n$  depend on physical assumptions.

# Boltzmann equation

In Carleman coordinates

$$\partial_t u + v \cdot \nabla_x u = Q(u, g) + \text{l.o.t.},$$

where

$$Q(u, g) = \text{p.v.} \int_{\mathbb{R}^n} \frac{u(t, x, v+h) - u(t, x, v)}{|h|^{n+2s}} m(g)(t, x, v, h) dh$$

with

$$m(g)(t, x, v, h) = \int_{w \perp h} g(t, x, v+w) |w|^{\gamma+2s+1} dw$$

and  $s \in (0, 1)$ ,  $\gamma > -n$  depend on physical assumptions.

## Boltzmann equation - linearised

Fix  $g$  and consider the linear equation

$$\partial_t u + v \cdot \nabla_x u = Au$$

where

$$Au = \text{p.v.} \int_{\mathbb{R}^n} \frac{u(t, x, v+h) - u(t, x, v)}{|h|^{n+2s}} m(g)(t, x, v, h) dh$$

with

$$m(g)(t, x, v, h) = \int_{w \perp h} g(t, x, v+w) |w|^{\gamma+2s+1} dw.$$

Even if  $g$  is very nice the density  $m(g)$  is degenerate.

## Boltzmann equation - linearised

Fix  $g$  and consider the linear equation

$$\partial_t u + v \cdot \nabla_x u = Au$$

where

$$Au = \text{p.v.} \int_{\mathbb{R}^n} \frac{u(t, x, v+h) - u(t, x, v)}{|h|^{n+2s}} m(g)(t, x, v, h) dh$$

with

$$m(g)(t, x, v, h) = \int_{w \perp h} g(t, x, v+w) |w|^{\gamma+2s+1} dw.$$

Even if  $g$  is very nice the density  $m(g)$  is degenerate.

Earlier Theorem is too restrictive for the Boltzmann equation!

# Vlasov-Poisson-Kolmogorov equation

$$\begin{cases} \partial_t u + v \cdot \nabla_x u + E(u) \cdot \nabla_v u = \nu \Delta_v u \\ u(0) = g \end{cases}$$

where

$$E(t, x) = \frac{\theta}{\sigma_{n-1}} \int_{\mathbb{R}^n} \frac{x - y}{|x - y|^n} M(u)(t, y) dy$$

with  $[M(u)](t, x) = \int_{\mathbb{R}^n} u(t, x, v) dv$ ,  $\theta = \pm 1$  and  $\nu > 0$ .

# Vlasov-Poisson-Kolmogorov equation

$$\begin{cases} \partial_t u + v \cdot \nabla_x u + E(u) \cdot \nabla_v u = \nu \Delta_v u \\ u(0) = g \end{cases}$$

Theorem (N. & Zacher):

Let  $p, q \in (1, \infty)$ ,  $\mu \in (1/p, 1]$  with  $\mu - 1/p > 2n/q$ ,  $j > n$  and  $k > n$  then for all initial values

$$g \in B_{qp,x,j,k}^{\frac{2}{3}(1-\frac{1}{p})}(\mathbb{R}^{2n}) \cap B_{qp,v,j,k}^{2(1-\frac{1}{p})}(\mathbb{R}^{2n})$$

there exists  $T = T(g)$  and  $\varepsilon > 0$  such that the VPK eq. admits a unique solution

$$u \in \left\{ u : u, \partial_t u + v \cdot \nabla_x u, \Delta_v u \in L_\mu^p((0, T); L_{j,k}^q(\mathbb{R}^{2n})) \right\}$$

for every initial value  $h \in \overline{B_\varepsilon(g)}^{X_{\gamma,\mu}}$ . Moreover, the solutions depend continuously on the initial value.

# Outlook

- relax assumptions for the variable coefficients (local/nonlocal)
- weak  $L^p$ -solutions
- boundary value problems
- sum of the operators  $\partial_t + v \cdot \nabla_x$  and  $A$  (non-commuting)
- Kinetic Fokker-Planck equation, i.e.  $A = \Delta_v + v \cdot \nabla_v$
- qualitative study of quasilinear problems such as  
global existence and large time behavior
- $L^p$ -theory of the Boltzmann equation

# Advertisement

## De Giorgi-Nash-Moser meets kinetic equations

Harnack inequality for kinetic equations

- first proof (GIMV 18); quantitative (GM 22)
- trajectorial interpretation of Moser's proof (elliptic/parabolic)
- trajectorial proof of a kinetic Poincaré inequality (used in GM 22)



L. N and R. Zacher. *A trajectorial interpretation of Moser's proof of the Harnack inequality.* Preprint. arXiv:2212.07977 (2022).



L. N and R. Zacher. *On a kinetic Poincaré inequality and beyond.* Preprint. arXiv:2212.03199 (2022).

# Bibliography

-  L. N., R. Zacher, *Kinetic maximal  $L^2$ -regularity for the (fractional) Kolmogorov equation.* Journal of Evolution Equations **21** (2021).
-  L. N., R. Zacher, *Kinetic maximal  $L^p$ -regularity with temporal weights and application to quasilinear kinetic diffusion equations.* Journal of Differential Equations **307** (2022).
-  L. N., Kinetic maximal  $L_\mu^p(L^p)$ -regularity for the fractional Kolmogorov equation with variable density. Nonlinear Analysis (2022).

[lukasniebel.github.io](https://lukasniebel.github.io)

